

Solving Master Equations. A simple tutorial.

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29 Sep 2014



Organisation of the Tutorial

1. Master Equations: notation, basic facts, and examples
2. Steady State
3. Generating Function Approach
4. Gardiner's Poisson Representation

References

1. Feller, W. (1968) **An introduction to Probability Theory and Its Applications**, vol.I & II, (3rd ed.). New York: John Wiley & Sons (old but still one of the best references for probabilists)
2. Gardiner, C. W. (2009). **Stochastic Methods: A Handbook for the Natural and Social Sciences** (4th ed.). Berlin: Springer. (quick and dirty)
3. Van Kampen, N. G. (2007). **Stochastic Processes in Physics and Chemistry** (3rd ed., p. 464). North Holland. (Stochastic processes the “physicist’s way”)
4. Norris, J. R. (1998). **Markov Chains** (p. 254). Cambridge: Cambridge University Press. (Elegant and thorough)

Markov Processes

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Sample space Ω

The set states or outcomes of the system

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\mathcal{F} : the sets of events

Formally σ -algebra on Ω that satisfies:

1. $\emptyset, \Omega \in \mathcal{F}$
2. If $A \in \mathcal{F}$ then $A^c \in \mathcal{F}$ (negation of events).
3. $\forall \{A_i\}_{i=0}^{\infty} : A_i \in \mathcal{F}, \bigcup_{i=0}^{\infty} A_i \in \mathcal{F}$

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π a (probability) measure

It must satisfy *Kolmogorov's Axioms*:

1. $\forall A \in \mathcal{F}, \pi(A) \in \mathbb{R}$ and $\pi(A) \geq 0$ (positivity)
2. $\pi(\Omega) = 1$ (unitarity or normalisation)
3. $\forall A_i \in \Omega : \forall i \neq j, A_i \cap A_j = \emptyset, \pi\left(\bigcup_{i=0}^{\infty} A_i\right) = \sum_{i=0}^{\infty} \pi(A_i)$

Stochastic Variable

Intuitively it is a function that takes different values according to the outcome of the system.

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Induced probability

The probability measure induces a probability on the stochastic variable $A \in \mathcal{E}$:

$$p_X(A) = \Pr(X(\omega) \in A) = \pi(X^{-1}(A)) = \int_{\omega} \mathbf{1}_{X^{-1}(A)} d\pi$$

Moments

On a stochastic X variable one can define a set of quantities that are called moments. The most commonly used are:

- ▶ **Mean:** $\mathbb{E}[X] = \int_{\Omega} X(\omega) d\pi(\omega) = \int_{X(\Omega)} x dp_X(A)$;
- ▶ **Variance:** $\text{Var}(X) = \mathbb{E}[(X - \mathbb{E}[X])^2]$;
- ▶ **Covariance:** $\text{Cov}(X) = \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])]$ if Y is another stochastic variable on the same space.

Stochastic Process

A stochastic process is a collection of (E, \mathcal{E}) stochastic variables on a probability space $(\Omega, \mathcal{F}, \pi)$ “indexed” by time i.e.

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where T is a totally ordered set. Typically T is \mathbb{R}_+ (continuous time processes) or \mathbb{Z} (discrete time).

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Natural Filtration

We define a set of events \mathcal{F}_t called *Natural Filtration* a σ -algebra on Ω such that:

1. $\mathcal{F}_t \subset \mathcal{F}$
2. $s < t \rightarrow \mathcal{F}_s \subset \mathcal{F}_t$
3. $\{X_s^{-1}(A) : s \leq t, A \in \mathcal{E}\} \subset \mathcal{F}_t$ (**Adaptivity**)
4. \mathcal{F}_t is the *coarsest* among

Markov Processes

To describe a system you need the joint probabilities for any choice of times for any set $A_{t_n} \subset \mathcal{E} \dots A_{t_0} \subset \mathcal{E}$:

$$\Pr(X_{t_n} \in A_{t_n} \dots X_{t_0} \in A_{t_0}) = \Pr(X_{t_n} \in A_{t_n} | X_{t_{n-1}} \in A_{t_{n-1}} \dots X_{t_0} \in A_{t_0}) \Pr(X_{t_{n-1}} \in A_{t_{n-1}} \dots X_{t_0} \in A_{t_0})$$

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Markov Property

For any $A, B \in \mathcal{E}$ for any $s, t \in T, s < t$

$$\Pr(X_t \in A | \mathcal{F}_s) = \Pr(X_t \in A | X_s \in B)$$

The knowledge of the one point functions $p(A, t) = \Pr(X_t \in A)$ and two point functions $p(A, t | B, s) = \Pr(X_t \in A | X_s \in B)$ (transition probabilities).

Markov Property: a natural scientist's perspective

Let's assume from now on that $E = \mathbb{R}^k$ or $E = \mathbb{Z}^k$ and the measures can be written in term either of a density or a discrete probability distribution.

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Markov Property : Discrete time

For a discrete time Markov Chain (i.e. $T = \mathbb{N}$), For all $A_i \in \mathcal{E}$ the markov property reads:

$$\Pr(X_n \in A \mid X_{n-1} \in A_{n-1}, \dots, X_0 \in A_0) = \Pr(X_n \in A_n \mid X_{n-1} \in A_{n-1})$$

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Simplified Markov Property for conuous time

For ant set $t_n, \dots, t_0 \in T, t_n > \dots t_0$ we have:

$$\Pr(X_{t_n} \in A_{t_n} \mid X_{t_{n-1}} \in A_{t_{n-1}}, \dots X_{t_0} \in A_{t_0}) = \Pr(X_{t_n} \in A_{t_n} \mid X_{t_{n-1}} \in A_{t_{n-1}})$$

Consequences of Markovianity

Any stochastic processes must satisfy consistency requirements.

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In a Markov Process this can be translated in a consistency requirement for transition probabilities.

Chapman-Kolmogorov equation for Markov processes

$$p(x, t | y, s) = \int_{X_0(\Omega)} p(x, t | z, t') p(z, t' | y, s) dz, \quad \forall t' : t > t' > s$$

Markov Jump processes. Continuous time Markov Chains

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$$P(\omega, t + dt | \omega', t) = \delta_{\omega\omega'} + Q_{\omega\omega'} dt + o(dt)$$

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Master Equation (Kolmogorov Forward Equation)

A differential version of C-K equation.

$$\partial_t P(\omega', t | \omega, s) = \left[\sum_{\xi} Q_{\omega\xi} P(\xi, t | \omega', s) \right] - \left[\sum_{\xi} Q_{\xi\omega} \right] \cdot P(\omega, t | \omega', s)$$

$$P(\omega, s | \omega' s) = \delta_{\omega'\omega}$$

Master Equations

The Master Equation can be written in a matricial form:

$$\partial_t P(t, \omega) = P(t, \omega) Q$$

$$P(s, s) = I$$

where $P(t, \omega)_{\omega\omega'} = P(\omega t | \omega' \omega)$.

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 $P(t, o) = e^{Q(t)}I$.

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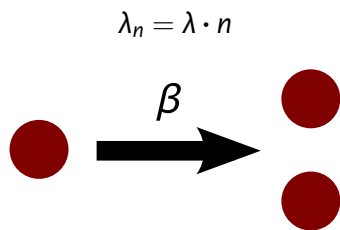
$$\sum_{\omega'} Q_{\omega\omega'} = 0$$

As a consequence

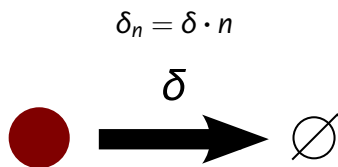
$$Q_{\omega\omega} = - \sum_{\omega' \neq \omega} Q_{\omega\omega'} = 0$$

Birth-Death processes

Birth Process



Death Process



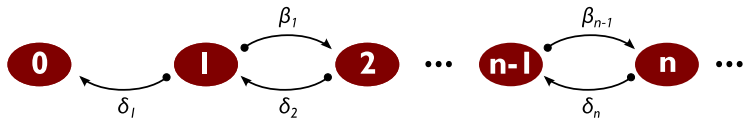
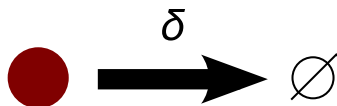
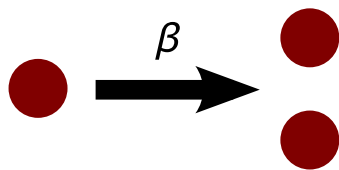
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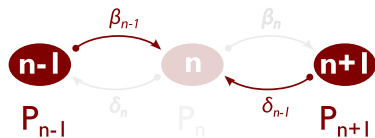
$$\lambda_n = \lambda \cdot n$$

$$\delta_n = \delta \cdot n$$

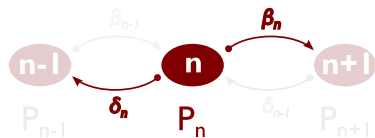


Master Equation for Birth-Death processes

Ingoing

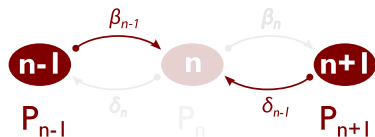


Outgoing

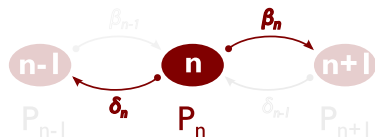


Master Equation for Birth-Death processes

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Outgoing



$$\partial_t P_n(t) = \delta \cdot (n+1) P_{n+1}(t) + \beta \cdot (n-1) \cdot P_{n-1}(t) - (\beta + \delta) n P_n(t)$$

Generalised birth-death processes

Accounts for interactions:

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Special cases

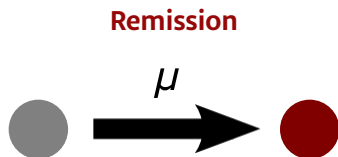
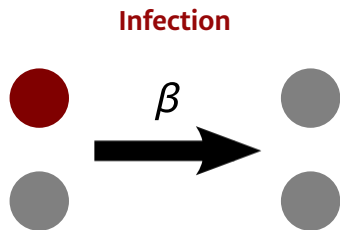
- ▶ $\delta_i = 0$ pure birth process
- ▶ $\beta_i = 0$ pure death process
- ▶ $\beta_i = \beta, \delta_i = 0$ Poisson process

Contact Processes: *SIS* model.

In a population of size N .

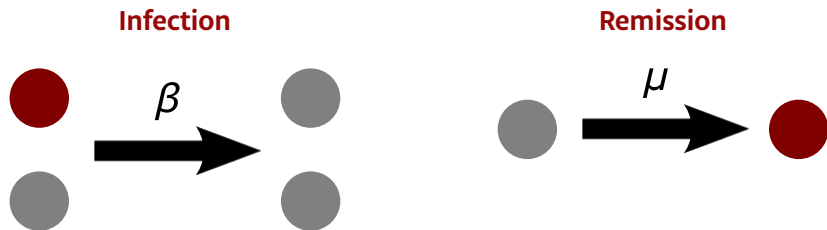
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Remember $S + I = N$

Long (long) Run

Invariant distribution

Master Equation defines an evolution operator for probabilities Π_t such that:

$$\Pi_t : P(\cdot; 0) \rightarrow P(\cdot; t)$$

Invariant distribution

An invariant distribution $\pi(\cdot)$ satisfies

$$\Pi_t(\pi(\cdot)) = \pi(\cdot)$$

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- ▶ If the states space is not finite this is not sure : Explosions.

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- ▶ If the states space is not finite this is not sure : Explosions. (e.g. Diffusion on a lattice).

Structure of State space

Transient Space

A subset $T \subset \Omega$ is said to be *transient* if for all $\tau \in T$ there exists a state $\omega \in \Omega$ such for finite $t > s$, $P(\omega t \mid \tau s) > 0$ and for any $t > s$, $P(\tau, t \mid \omega, s) = 0$. An invariant distribution π must satisfy $\pi|_T = 0$.

Irreducible Subspace

A subset $I \subset \Omega$ is said *irreducible* if for any two states $\omega_0, \omega' \in I$ there exists a finite sequence $\{\omega_1, \omega_n\}$ such that $Q_{\omega_0\omega_1} \cdot \dots \cdot Q_{\omega_n\omega'} > 0$ and $Q_{\omega_0\omega_1} \cdot \dots \cdot Q_{\omega_n\omega'} > 0$

Ergodic Subspace

An irreducible subset is *ergodic* if it is *positive recurrent*: i.e. the expected return time for any state is finite. If the state space is finite any irreducible subset is ergodic.

Finding the Invariant distribution: Detailed balance

The invariant distributions satisfies:

$$\left[\sum_{\xi} Q_{\omega\xi} P(\xi, t | \omega', s) \right] - \left[\sum_{\xi} Q_{\xi\omega} \right] \cdot P(\omega, t | \omega', s) = 0$$

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detailed balance

A simplified condition. Implies time invariance thus equilibrium
Reversibility.

$$Q_{\omega'\omega} \pi(\omega') = Q_{\omega\omega'} \pi(\omega)$$

Example: birth-death

Absorbing State

When $\beta_0 = 0$, the subset $E = \{N = 0\}$ is clearly ergodic. It is called **absorbing state** and the stationary distribution $\pi_n = \delta_{0n}$ is clearly an invariant distribution.

In general we should solve the equation:

$$P_{n+1}\delta(n+1) - P_n(\beta + \delta)n + \beta(n-1)P_{n-1} = 0, \quad n \geq 1$$
$$\delta P(1) = 0$$

Clearly, the absorbing solution is the only invariant solution.

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Clearly, the absorbing solution is the only invariant solution.

Question: does the system always reach the equilibrium solution?

Answer: It depends on the dynamics and the initial state!

Example: generalized birth death process

In this case it depends on the rate. Since the space is irreducible one should check that it is also recurrent. Applying detailed balance we get:

$$P_k = P_0 \prod_{i=0}^{n-1} \frac{\beta_i}{\delta_i}$$

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Ergodicity Condition

If all $\beta_i \neq 0$ and $\delta_i \neq 0$

$$\sum_n \prod_{i=0}^{n-1} \frac{\beta_i}{\delta_i} < +\infty$$

Which thus gives an extinction probability of:

$$P_0 = \frac{1}{1 + \sum_n \prod_{i=0}^{n-1} \frac{\beta_i}{\delta_i}}$$

Example: SIS

If we write $S = N - I$ we can rewrite the master equation as SIS:

$$\partial_t P(I; t) = \beta \frac{I-1}{N} (N - I + 1) P(I-1; t) + \mu (I+1) \cdot P(I+1; t) - \left(\beta \frac{I}{N} (N - I) + \mu I \right) P(I; t), \quad 0 < I \leq N$$

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finite state-space: The system always converge to a stationary solution

- ▶ $E = \{I = 0\}$ Is clearly ergodic (absorbing state).
- ▶ The set $T = \{0 < I \leq N\}$ is *transient*, i.e. there is a finite probability of reaching the absorbing state thus. Since the state space is finite $\lim_{t \rightarrow \infty} P(t) = \delta_{I0}$

Long run: recap.

- ▶ Look at the state space, find the ergodic subspaces to know how many invariant distribution you may expect.
- ▶ Try Detailed balance;
- ▶ Try to solve the general recurrence;

Generating function Method

Generating Function theorems

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Probability Generating Function

$$G(t; \vec{z}) = \mathbb{E}[\vec{z}^{X_t}] \text{ **Mellin Transform**}$$

Probability Generating Function: properties (univariate)

Generates Probabilities

$$\frac{1}{n!} \partial_z^n G(t; z) \Big|_{z=0} = P_n$$

Normalisation

$$G(t; \vec{1}) = \sum_n P_n(t) = 1$$

Moments

$$(z \partial_z)^k G(t; z) \Big|_1 = \sum_{n=1}^{\infty} n^k P_n(t) = \mathbb{E}[X_t^k]$$

Probability generating function for Birth-death

$$G(t, z) = \sum_{k=0}^{\infty} z^k P_k(t).$$

Plugging it in the master equation

$$\sum_n z^n \partial_t P_n(t) = \sum_{n \geq 1} \beta (n-1) z^n P_{n-1}(t) + \sum_{n \geq 0} \delta (n+1) z^n P_{n+1}(t) - (\beta + \delta) n z^n P_n(t)$$

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- ▶ $\sum_{n \geq 0} (\beta + \delta) n z^n P_n \rightarrow z(\beta + \delta) \partial_z G(t; z)$

Generating function equations

We thus mapped Master equation in :

$$\partial_t G(t; z) = [\beta z^2 - (\beta + \delta)z + \delta] \partial_z G(t; z)$$

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Method of Characteristics

$z \rightarrow Z(s)$ and $t \rightarrow T(s)$.

$$\frac{dG(T(s); Z(s))}{ds} = \partial_z G(T(s); Z(s)) \frac{dZ}{ds} + \partial_t G(T(s); Z(s)) \frac{dT}{ds}$$

You transform it in a set of ODE

$$\begin{cases} Z'(s) = -(\beta Z^2 - Z(\beta + \delta) + \delta) \\ T'(s) = 1 \\ G' = 0 \end{cases}$$

Solution

- ▶ $T'(s) = 1$ implies $s = t$,
- ▶ $G' = 0$ implies $G(z, t) = G(z_0, 0) = G_0(z) = \sum_n z^n P_n(0)$;
- ▶ for a $P_k(0) = \delta_{kN_0}$ implies $G_0(z_0) = (z_0)^{N_0}$.

$$\text{▶ } z_0 = \frac{\frac{\delta}{\beta} + \frac{e^{-t(\beta-\delta)}\left(z - \frac{\delta}{\beta}\right)}{1-z}}{1 + \frac{e^{-t(\beta-\delta)}\left(z - \frac{\delta}{\beta}\right)}{1-z}}$$

$$G(z, t) = G_0 \left[\frac{\frac{\delta}{\beta} + \frac{e^{-t(\beta-\delta)}\left(z - \frac{\delta}{\beta}\right)}{1-z}}{1 + \frac{e^{-t(\beta-\delta)}\left(z - \frac{\delta}{\beta}\right)}{1-z}} \right] = \left[\frac{\frac{\delta}{\beta} + \frac{e^{-t(\beta-\delta)}\left(z - \frac{\delta}{\beta}\right)}{1-z}}{1 + \frac{e^{-t(\beta-\delta)}\left(z - \frac{\delta}{\beta}\right)}{1-z}} \right]^{N_0}$$

Active/Absorbing transition

$$P_o(\infty) = \begin{cases} 1 & \text{if } \frac{\beta}{\delta} \leq 1 \\ \left(\frac{\delta}{\beta}\right)^N & \text{otherwise} \end{cases}$$

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$$\text{Var}[N(t)] = z \partial_z G(z, t) + z^2 \partial_z G_{z,t} - z^2 (\partial_z G(z, t))^2 \Big|_{z=1} = \frac{N(\beta+\delta)e^{t(\beta-\delta)}(e^{t(\beta-\delta)}-1)}{\beta-\delta}$$

Recap.

- ▶ Choose your generating function (different Generating function originates difference)
- ▶ Transform the system in a PDE
- ▶ Solve it!
- ▶ Retrieve the Pdf or the moments.

Gardiner's Poisson representation

Main ideas

- ▶ Many process are “close to poissonianity”
- ▶ The main idea is to average it out and find equations for the non Poissonian part
- ▶ It is a transform of the pdf.

The method

Poisson Transform

$$P_n(t) = \int_0^{\infty} f(a, t) \frac{e^{-a} a^n}{n!} da$$

with the condition: $\int_0^{\infty} f(a, t) da = 1$

Master Equation \Rightarrow PDE for $f(a, t)$

Advantages

- ▶ You can calculate easily the moments:

$$\mathbb{E}[N_t] = \int \sum_n \left[\frac{na^n}{n!} e^{-a} \right] f(a, t) da = \int_0^\infty af(a, t) da$$

$$\mathbb{E}[N_t^2] = \int \sum_n \left[\frac{n^2 a^n}{n!} e^{-a} \right] f(a, t) da = \int_0^\infty (a^2 + a)f(a, t) da$$

- ▶ A continuous limit **for free**

Example: birth-death

- ▶ $\partial_t P_{n-1}(t) = \int_0^\infty \partial_t f(a, t) \frac{e^{-a} a^n}{n!} da$
- ▶ $(\beta + \delta)nP_n = -(\beta + \delta) \int_0^\infty [(1-a)f(a, t) + a\partial_a f(a, t)] \frac{e^{-a} a^n}{n!} da$
- ▶ $\delta(n+1)P_{n+1} = \delta \int_0^\infty af(a, t) \frac{e^{-a} a^n}{n!} da$
- ▶ $\beta(n-1)P_{n-1} =$
 $\beta \int_0^\infty [\beta(a-2) + 2(a-1)\partial_a f(a, t) + a\partial_a^2 f(a, t)] \frac{e^{-a} a^n}{n!} da$

Poisson Representation for Birth-Death processes

$$\partial_t f(a, t) = \partial_a \left[(\delta - \beta)af(a, t) + \frac{1}{2}\partial_a(2\beta af(a, t)) \right]$$

Thank you!